

## 8.4 Exponential Matrix

In this section we look at a different way for solving the homogeneous system  $\mathbf{X}' = \mathbf{A}\mathbf{X}$  that involves the concept of exponential matrix which we define next.

For any  $n \times n$  matrix  $\mathbf{A}$  of constant entries, we define the **exponential matrix**

$$e^{\mathbf{A}t} = \mathbf{I} + \mathbf{A}t + \frac{\mathbf{A}^2 t^2}{2!} + \cdots + \frac{\mathbf{A}^n t^n}{n!} + \cdots = \sum_{n=0}^{\infty} \frac{\mathbf{A}^n t^n}{n!}$$

where  $\mathbf{I}$  is the matrix with 1 on the main diagonal and 0 elsewhere. Also,  $\mathbf{A}^n = \mathbf{A}(\mathbf{A}^{n-1})$ .

### Example 8.4.1

Find  $e^{\mathbf{A}t}$  if  $\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ .

**Solution.**

We have

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2^1 \end{bmatrix} \\ \mathbf{A}^2 &= \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2^2 \end{bmatrix} \\ \mathbf{A}^3 &= \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2^3 \end{bmatrix} \\ \mathbf{A}^4 &= \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2^4 \end{bmatrix} \end{aligned}$$

Inductively, we have

$$\mathbf{A}^k = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2^{k-1} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2^k \end{bmatrix}.$$

Hence,

$$\begin{aligned}
 e^{\mathbf{A}t} &= \mathbf{I} + \mathbf{A}t + \frac{\mathbf{A}^2 t^2}{2!} + \cdots + \frac{\mathbf{A}^n t^n}{n!} + \cdots \\
 &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \frac{t}{1!} + \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} \frac{t^2}{2!} + \cdots \\
 &= \begin{bmatrix} 1 + \frac{t}{1!} + \frac{t^2}{2!} + \cdots & 0 \\ 0 & 1 + \frac{(2t)}{1!} + \frac{(2t)^2}{2!} + \cdots \end{bmatrix} = \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \blacksquare
 \end{aligned}$$

Next, we find the derivative of  $e^{\mathbf{A}t}$ . We have

$$\begin{aligned}
 \frac{d}{dt} e^{\mathbf{A}t} &= \frac{d}{dt} \left[ \mathbf{I} + \mathbf{A}t + \frac{\mathbf{A}^2 t^2}{2!} + \cdots + \frac{\mathbf{A}^n t^n}{n!} + \cdots \right] \\
 &= \mathbf{A} + \mathbf{A}^2 t + \mathbf{A}^3 \frac{t^2}{2!} + \mathbf{A}^4 \frac{t^3}{3!} \cdots \\
 &= \mathbf{A} \left[ \mathbf{I} + \mathbf{A}t + \frac{\mathbf{A}^2 t^2}{2!} + \cdots \right] = \mathbf{A} e^{\mathbf{A}t}.
 \end{aligned}$$

Next, we will show that  $\mathbf{X} = e^{\mathbf{A}t}\mathbf{C}$  is a solution to the homogeneous system  $\mathbf{X}' = \mathbf{A}\mathbf{X}$ . Indeed,

$$\mathbf{X}' = \mathbf{A}e^{\mathbf{A}t}\mathbf{C} = \mathbf{A}\mathbf{X}.$$

### Example 8.4.2

Using exponential matrices, find the general solution to  $\mathbf{X}' = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{X}$ .

**Solution.**

We have

$$\mathbf{X} = e^{\mathbf{A}t}\mathbf{C} = \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = c_1 \begin{bmatrix} e^t \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ e^{2t} \end{bmatrix} \blacksquare$$

Exponential matrices can be used to solve the non-homogeneous system  $\mathbf{X}' = \mathbf{A}\mathbf{X} + \mathbf{F}$ . The complementary solution is found as above and the particular solution to the non-homogeneous system is

$$\mathbf{X}_p = e^{\mathbf{A}t} \int_{t_0}^t e^{-\mathbf{A}s} \mathbf{F}(s) ds.$$

Indeed,

$$\mathbf{X}'_p = e^{\mathbf{A}t} e^{-\mathbf{A}t} \mathbf{F}(t) + \mathbf{A} e^{\mathbf{A}t} \int_{t_0}^t e^{-\mathbf{A}s} \mathbf{F}(s) ds = \mathbf{A}\mathbf{X}_p + \mathbf{F}.$$

**Example 8.4.3**

Using exponential matrices, find the general solution to

$$\mathbf{X}' = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{X} + \begin{bmatrix} 3 \\ -1 \end{bmatrix}.$$

**Solution.**

From Example 8.4.2, we found

$$\mathbf{X}_c = c_1 \begin{bmatrix} e^t \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ e^{2t} \end{bmatrix} = \begin{bmatrix} c_1 e^t \\ c_2 e^{2t} \end{bmatrix}.$$

The complementary solution is

$$\begin{aligned} \mathbf{X}_p &= \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \int_0^t \begin{bmatrix} e^{-s} & 0 \\ 0 & e^{-2s} \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} ds \\ &= \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \int_0^t \begin{bmatrix} 3e^{-s} \\ -e^{-2s} \end{bmatrix} ds \\ &= \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \left[ \begin{array}{l} -3e^{-s} \\ \frac{1}{2}e^{-2s} \end{array} \right]_0^t \\ &= \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \left[ \begin{array}{l} -3e^{-t} + 3 \\ \frac{1}{2}e^{-2t} - \frac{1}{2} \end{array} \right]_0^t \\ &= \begin{bmatrix} -3 + 3e^t \\ \frac{1}{2} - \frac{1}{2}e^{2t} \end{bmatrix}. \end{aligned}$$

Hence, the general solution is

$$\mathbf{X}(t) = \begin{bmatrix} c_1 e^t \\ c_2 e^{2t} \end{bmatrix} + \begin{bmatrix} -3 + 3e^t \\ \frac{1}{2} - \frac{1}{2}e^{2t} \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^t + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{2t} + \begin{bmatrix} -3 \\ \frac{1}{2} \end{bmatrix} \quad \blacksquare$$

**Finding  $e^{\mathbf{A}t}$  Using the Laplace Transform**

We can find  $e^{\mathbf{A}t}$  by using Laplace transform. Indeed,  $\mathbf{X} = e^{\mathbf{A}t}$  satisfies the initial value problem  $\mathbf{X}' = \mathbf{A}\mathbf{X}$ ,  $\mathbf{X}(0) = \mathbf{I}$ . Moreover,

$$s\mathcal{L}(\mathbf{X}) - \mathbf{X}(0) = \mathbf{A}\mathcal{L}(\mathbf{X}) \Rightarrow (s\mathbf{I} - \mathbf{A})\mathcal{L}(\mathbf{X}) = \mathbf{I}.$$

Thus,

$$\mathbf{X} = e^{\mathbf{A}t} = \mathcal{L}^{-1}[(s\mathbf{I} - \mathbf{A})^{-1}].$$

**Example 8.4.4**

Use the Laplace transform to compute  $e^{\mathbf{A}t}$  where  $\begin{bmatrix} 4 & 3 \\ -4 & -4 \end{bmatrix}$ .

**Solution.**

We have

$$\begin{aligned} s\mathbf{I} - \mathbf{A} &= \begin{bmatrix} s-4 & -3 \\ 4 & s+4 \end{bmatrix} \\ (s\mathbf{I} - \mathbf{A})^{-1} &= \begin{bmatrix} \frac{s+4}{s^2-4} & \frac{3}{s^2-4} \\ -\frac{4}{s^2-4} & \frac{s-4}{s^2-4} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\frac{3}{2}}{s-2} - \frac{\frac{1}{2}}{s+2} & \frac{\frac{3}{4}}{s-2} - \frac{\frac{3}{4}}{s+2} \\ -\frac{1}{s-2} + \frac{1}{s+2} & \frac{-\frac{1}{2}}{s-2} + \frac{\frac{3}{2}}{s+2} \end{bmatrix} \\ e^{\mathbf{A}t} &= \mathcal{L}^{-1} \left( \begin{bmatrix} \frac{\frac{3}{2}}{s-2} - \frac{\frac{1}{2}}{s+2} & \frac{\frac{3}{4}}{s-2} - \frac{\frac{3}{4}}{s+2} \\ -\frac{1}{s-2} + \frac{1}{s+2} & \frac{-\frac{1}{2}}{s-2} + \frac{\frac{3}{2}}{s+2} \end{bmatrix} \right) \\ &= \begin{bmatrix} \frac{3}{2}e^{2t} - \frac{1}{2}e^{-2t} & \frac{3}{4}e^{2t} - \frac{3}{4}e^{-2t} \\ -e^{2t} + e^{-2t} & -\frac{1}{2}e^{2t} + \frac{3}{2}e^{-2t} \end{bmatrix} \blacksquare \end{aligned}$$